

| MXC Smart-Tactor™

CAN-BUS CONTACTOR

Introduction

Automatic trip function 350 amp and 600 amp versions CAN-BUS Communication





EPIC Seal	Ceramic to metal braze. Gas filled hermetic chamber protects key component Exceeds IP69K standard		
Contacts / Form	Silver / SPST / NO		
Coil	Efficient two coil design with no PWM or EMI emissions.		
Suppression	Coil suppression built in		
High Shock and Vibration	For rugged environments, off-road and tracked vehicles		
Installation	Not orientation sensitive		
Reference	MIL-R-6106, RoHS		

Coil Ratings (25°C, Currents & Power At Nominal V)

Series	15 (350A)		16 (600A)		
Coil P/N Designation	В	С	В	С	
Coil Voltage (Nominal)	12	24	12	24	V
Coil Voltage (max)	16	32	16	32	V
Coil Voltage (min)	9	17	9	17	V
Inrush Current (max)	3.9	1.6	3.8	1.9	А
Hold Current after inrush (max)	0.23	0.097	0.64	0.32	А
Coil Hold Power (max)	2.8	2.3	7.7	7.8	W
Coil Back EMF*	0			V	
Transient on all pins	+50V 13ms				
Reverse polarity on all pins	-80			V	

^{*}Coils are switched internally with a FET, so no fly-back/suppression voltage is seen at the coil inputs.



Contacts

Series	15 (350A)	16 (600A)	
Contact form	SPST-NO		
Contact Voltage Rating	12-48V		
Insulation resistance, A1-A2 and A1&A2 to controls	500V, 100Μ Ω (50Μ Ω after life)		
Dielectric, A1-A2 and A1&A2 to controls	2200VAC, 60Hz, 1mA		
Contact Resistance (max)	1.5 m Ω (.4 avg)		
Current (see chart for Temp. derating)	350A 400MCM	600A 500MCM	
90s	1000A	1500A	
10s	2000A	3000A	
1s	3000A 4000A		

Resistive Load Switching

Series	15 (350A)	16 (600A)		
Fault interrupt (1 cycle)	3000A	5000A		
Resistive switching @ 28V	100,000 cycles @ 350A	100,000 cycles @ 600A		
Please contact factory for more detailed resitive switching specifications.				
Mechanical life	300,000 cycles			

Environmental Specifications

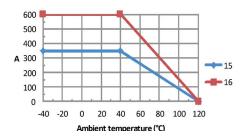
Series	15 (350A)	16 (600A)	
Weight (Max, with hardware)	1.6lbs, 725g	2lbs, 910g	
Vibration (10 - 2000Hz)	15G		
Shock, 1/2 Sine, 11ms	20G		
Temperature Range (ambient)	-40°C to 85°C		
Max Terminal Temperature	125°C		
Water Resistance	IP67 and IP69K		
Seal: Hermetic Vacuum Braze, tested to E-9 std cc/sec			
Steam/Water-Jet/Boiling Water	105psi Steam/2750psi Jet/ Submersion in BW		
Chemicals, Corrosion, Fungal Growth	Resistant		

Timing (Max Values @ 25°C)

Series	15 (350A) 16 (600A)			600A)
Operate (including bounce)	20ms			
Inrush	75ms			
Release	12	ms	7ms	
For details, contact factory for App. Note	#8	#9	#12	#13



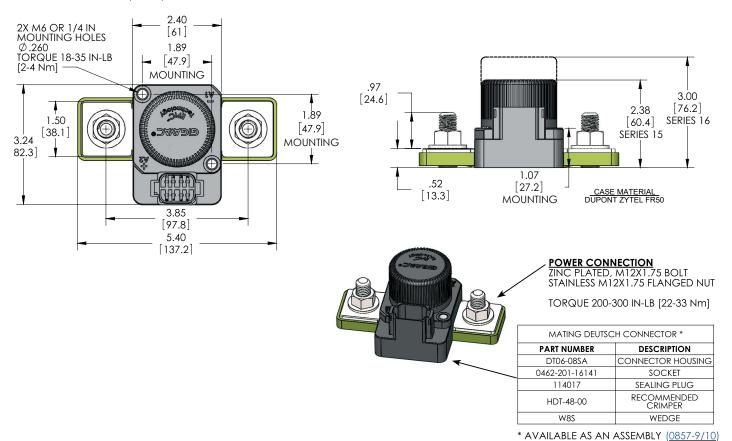
CURRENT CARRY



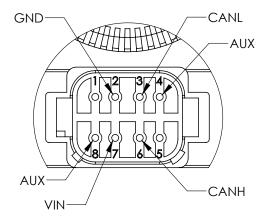
GIGAVAC®

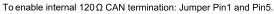


Dimensions are in millimeters [inches] Coil terminal polarity is X1 (+) and X2 (-)



POWER CIRCUIT AND INSTALLATION





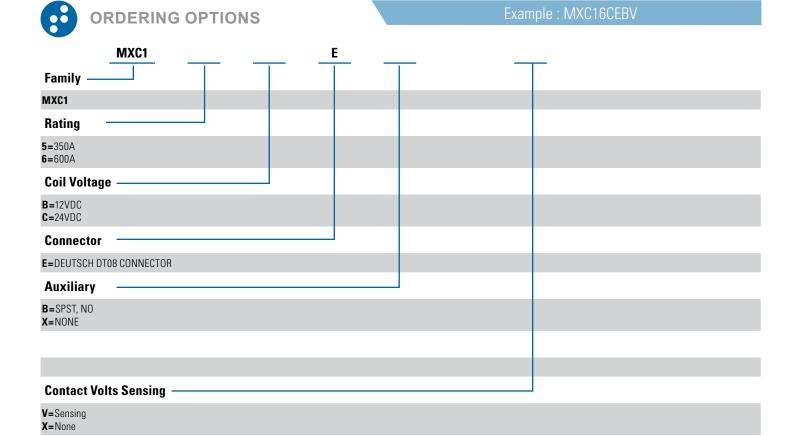
A2(+) O O A1(-) COIL Pin7(VIN) PCBA/ CONTROL Pin3(CANL)

Settings Parameters

Current Sense Accuracy	±7%		
Over Current Response Time	2ms + release time 20ms		

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GENERAL NOTES

- 1. Contactor has two coils. Both are used for pull-in. After approx mately 75 milliseconds, one coil is electronically removed from the coil drive circuit. The remaining coil supplies low continuous hold power sufficient for the contactor to meet all of its specified performance specifications. This provides the lowest coil power possible without the use of PWM electronics that have been known to cause EMI emissions and/or crosstalk on system control power.
- 2. Control and Communication Protocol: J1939 (Link to DBC file to be added)
- Features
- 4. Read: device ID, rmware version, current, temperature, contactor cycle-log and optional nonisolated contact-volts sensing.
- 5. Read/Write: power supply under-voltage-shutoff, contactor (open/close), trip points, trip delays, power up default (open/close).
- 6. Visit www.gigavac.com for the latest CAN-BUS protocol information.

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